

Smile100

V1.0

2025/**/**

BOM

518057

www.megmeet-drivetech.com

(0755) 8660 0500

<https://www.megmeet.com>

400-666-2163

Smile100

Smile100

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 危險	
 警告	
	

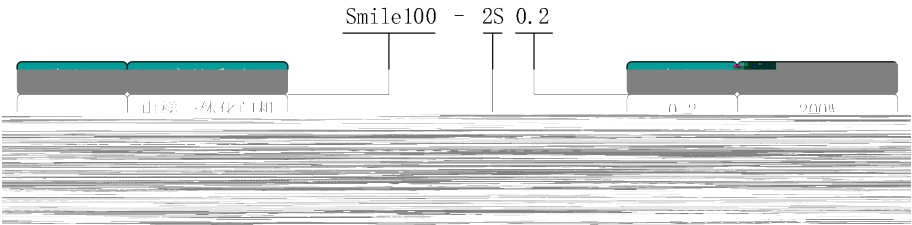
Smile100	1
	2
	1
1.1	1
1.1.1	1
1.1.2	1
1.2	1
1.3	2
1.4	3
1.5	3
1.6	4
	5
2.1	5
2.2	5
2.2.1	5
2.2.2	6
2.2.3	6
2.2.4	6
2.2.5	7
2.3	7
2.3.1	7
2.3.2	7
2.3.3	8
	9
3.1	9
3.2	10
	11
4.1	11
4.2	11
4.3	12
4.4	13
	14
5.1	14
5.2	15
5.2.1	16
5.2.2	16
5.2.3	17
5.2.4	17
	18
6.1	18
6.2	18
6.2	19
A	33

1.1

1.1.1



1.1.2



1.2

	kVA	A		A	W
	220V	220	240V	50/60Hz	
Smile100-2S0.2	0.4	2.2		1.2	200
Smile100-2S0.4	0.8	4.5		2.3	400

1.3



200 240V ± 10%
50/60Hz ± 5%
0
0 99.99Hz



SVC VC
1 100 SVC 1 1000 VC
± 0.5% SVC ± 0.05% VC
0.5Hz 180% SVC 0Hz 180% VC

0.01Hz 0.01A
150% 1 180% 1

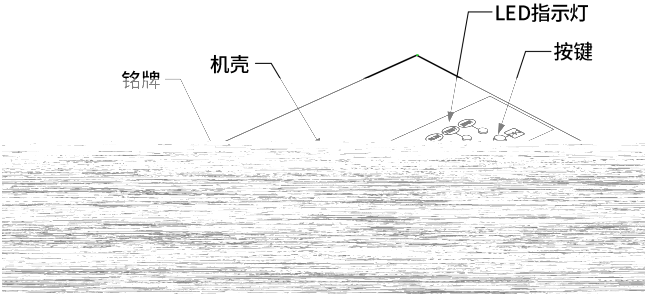


ABZ

0/60

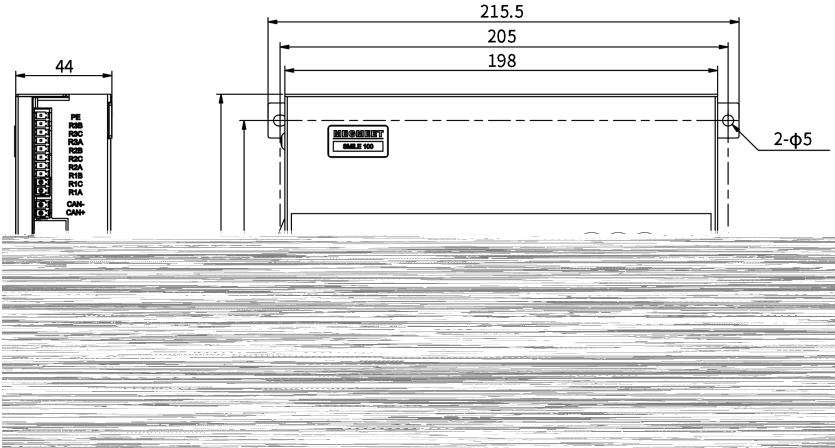
	2	9Hz	3.5m/s²	9	200Hz	10m/s²	IEC60721-3-3
	IP20						
	2						
	LED						

1.4



1-1

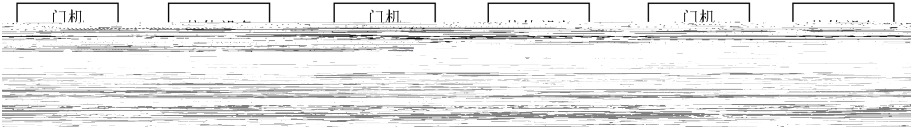
1.5



1-2

2.1

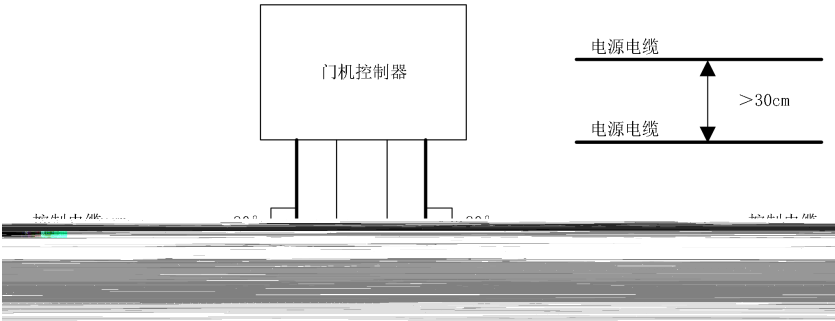




2-1

2.2.2

90 ° 2-2



2-2

2.2.3

警告

◇ U/V/W

◇ Smile100

◇

3*1mm²

2.2.4

3*1mm²

2.2.5

50

2.3

2.3.1



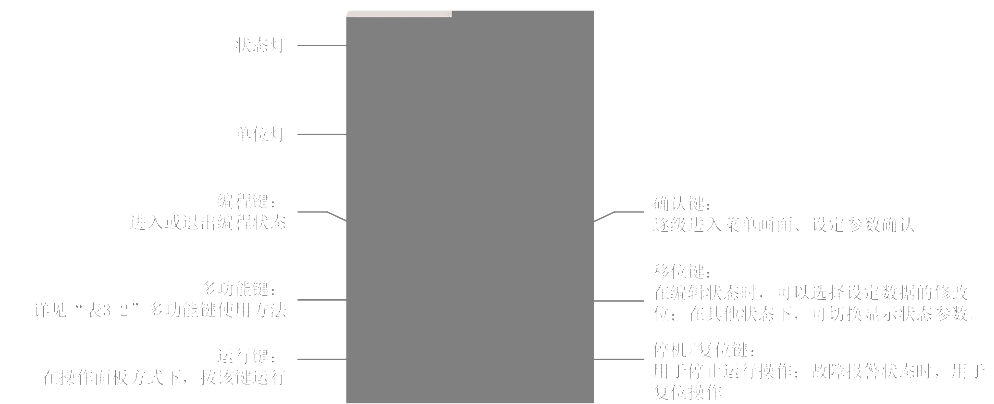
Smile100

		/	
		/	
	R1A/R1B/R1C		RA-RB 250VAC/5A DC30V/5A 2.5kVAC
	R2A/R2B/R2C		
	R3A/R3B/R3C		
	RS485+	485	RJ45
	RS485-	485	
	CANH	CAN	CAN
	CANL	CAN	
		APP	APP
	COM		24V
	PGZ	Z	
	PGB	B	
	PGA	A	
	24V	24V	
	P24V	24V	24V 200mA
	COM	24V	

2.3.3

			220V
			380V
			10A
			D

3.1



3-1

3-1

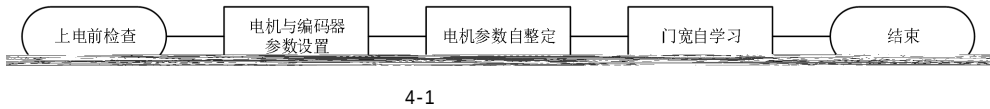
FWD			
REV			
ALARM			
QUICK		QUICK BASIC	
BASIC			
Hz			
A			
V			
m/s			
r/min			

3-2		
0		M
1	JOG	M JOG
2	FWD/REV	M FWD/REV
3	1	M → M → M M
4	2	M
5		M M 5 M 0
6		M VF
7		M

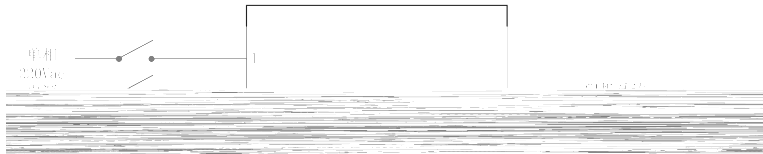
3.2

3-1

-
-
-



4.1



4-2

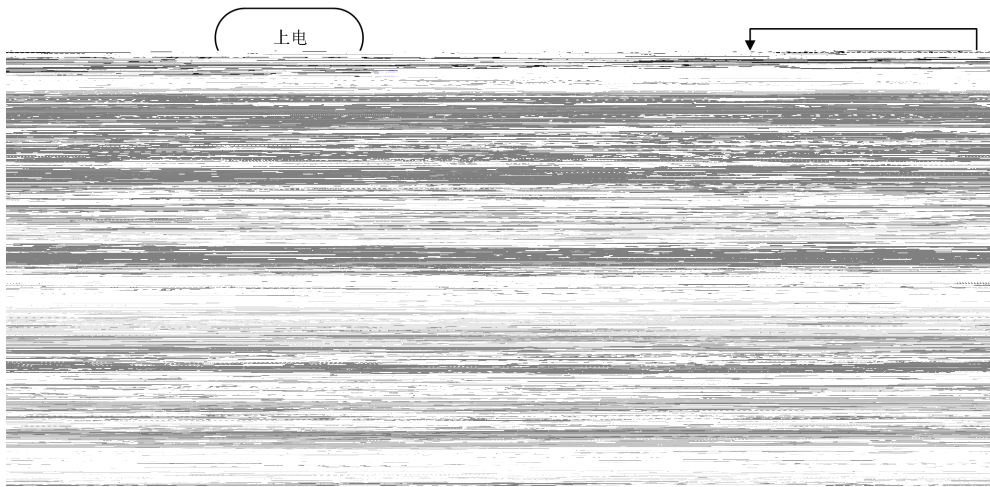


4.2

-
-
-

4.3

D01.00



4-3

P01.00		1 750W	
P01.01		1 300V	
P01.02		0.1 2.5A	
P01.03		1.00Hz 99.99Hz	
P01.04		1 6000rpm	
P01.05		1.00 9.99	
P01.06		0 1	P01.06=1
P02.00		0 9999	

◇

◇

◇

◇

◇

Smile100

U V W

Smile100

STOP

4.4

1

P00.02

1

2

P02.05

1

P00.03

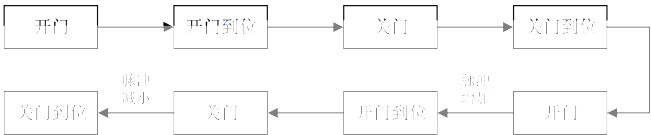
0

RUN

P02.05

0

STOP



4-4

1

Smi le100

U/V/W

2

3

P02.01

E26

P05.14

5.1

Smile100

1 STOP
2 DI 9
3

P09

5-1

E01			P03.05 P04.05
E02			Smile100 P01.00 P01.04 P03.02 P04.02 P03.05 P04.05
E03			Smile100 P01.00 P01.04 P03.02 P04.02 P03.05 P04.05
E04	Z		Z
E06		Z	P01.00 P01.04
E07			
E08		P06.28 =1	

E09			
E10		10	
E11			
E12		20	
E14	EEPROM	EEPROM	
E15		P10.16 P10.15	P10.15 P10.16
E16		P10.18 P10.17	P10.17 P10.18
E17			
E18			
E22	EEPROM	EEPROM	
E23			P02.00
E26			P02.04
E100			/

5.2

- 1
- 2



◇
◇

5.2.3

6.1

“ ○ ”
“ × ”
“ * ”

6.2

Smile100

0

“

“

“STOP
RESET

”

”

1

Smile100

P00.03 =1 Smile100

OD			CD		
P06.15 0			P06.15 1		
OD	CD		OD	CD	
0	0		0	0	
0	1		0	1	
1	0		1	0	
1	1		1	1	

2

P00.03 = 0

P08

STOP

“

“

STOP
RESET

”

”

OD/CD COM

3

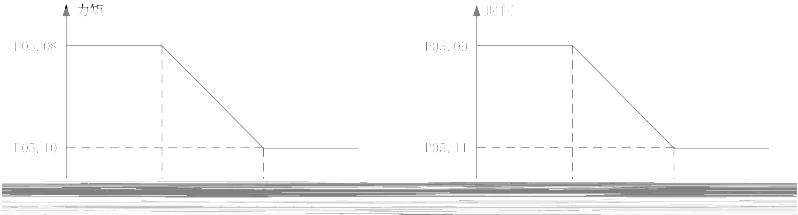
P00.04		1.00 99.99Hz	50.00Hz	×
Smile100				
P00.05		0 1	0	×
0				
1 S				
P00.06		0 3	2	×
0				
1				
2				
3				
P01				
P01.00		1 750W	50W	×
P01.01		1 300V	220V	×
P01.02		0.10 2.5A	1.1A	×
P01.03		1.00Hz 99.99Hz	24.00Hz	×
P01.04		1 6000rpm	900rpm	×
P01.05		1.00 9.99	1.00	×
P01.05 1.00				
P00.06=1				
P01.06		0 1	0	×

21

P02.07		0 9999		0	×
=P02.07×10000+P02.06		P02.06		P02.07	
P02.08		0 9999		0	×
DI		4 14		P06.15 1	
P03					
P6 The diagram illustrates a motor speed profile. It starts with an acceleration phase (加速) defined by starting distance P03.00 and acceleration time P03.02. This is followed by a constant speed phase (开门速度) at P03.03. The deceleration phase (减速) is defined by deceleration time P03.05. A specific deceleration point is marked as P03.04. The profile ends with a stop phase (停止) where the switching torque is P05.00 and the holding torque is P05.03. The final state is labeled '最终'.					
P03.00		0 9999		576	○
P03.00 P03.00 ms					
P03.01		0 15.00Hz		3.50Hz	○
P03.02		0.1 99.9s		1.3s	○
P03.03		0.00	P00.04	20.00Hz	○
P03.04		50.0% 90.0%		65.00%	○
≥ P03.04 × P03.03 P03.06 P03.04					
P03.05		0.1 99.9s		2.0s	○
P00.04					
P03.06		0 15.00Hz		3.00Hz	○
P03.07		80.0 99.9%		90.0%	○
P03.07 ×					
P03.08		10.0% 90.0%		90.00%	○
P03.08					

P03.08=70.0% 100-70=30 0 30%				
30 100%				
P04				
P6				
				
P04.00		0 9999	0	○
P04.00 P04.00 ms				
P04.01		0.00 15.00Hz	4.00Hz	○
P04.02		0.1 99.9s	2.0s	○
P04.03		0.00 P00.04	18.00Hz	○
P04.04		50.0% 90.0%	62.00%	○
≥ 1-P04.04 × P04.03 P04.06 P04.04				
P04.05		0.1 99.9s	2.0s	○
P04.06		0.00 15.00Hz	1.5Hz	○
P04.07		0 5000	0	○
P04.07 ≤ P04.07 P04.07 ms				
P04.08		0 15.00Hz	0.00Hz	○
P04.07				
P04.09		1 500	60	○
P04.10		0.00 5.00Hz	0.00Hz	○
P04.11		0 5000	0	○
P04.11 ≤ P04.11 ms P04.11				
P05				

Smile100

P05.00		20.0% P07.07	50.00%	○
P03.07 × ≥ P05.00 ×				
P05.01		30.0% P07.07	45.00%	○
≥ P05.00 × P05.01 ×				
P05.02		0.0 P07.07	35.00%	○
P05.03		0.1 999.9s	30.0s	○
P05.01 P05.03 P05.02				
P05.04		20.0% P07.07	50.00%	○
P05.05		30.0% P07.07	45.00%	○
P05.06		0.0 P07.07	35.00%	○
P05.07		0.1 999.9s	60.0s	○
P05.08		0.0% P07.07%	100.00%	○
P05.09		0 4999ms	1000ms	×
P05.10		0.0% P07.07%	100.00%	○
P05.11		0 4999ms	1000ms	×
P05.12		0.00 P00.04	5	×
P05.13		0.00 P00.04	15	×
P05.08 P05.10 P06.13 				
P05.14		30.0 P07.07	70.0%	○
P05.15		0.0 P07.07	100.00%	○
P05.16		0 4999ms	1600ms	×
P05.15 P05.15 0 P05.16				

P05.17		0 9999ms	3000ms	×
P05.17				
P05.17=9999ms				
P06				
P06.00	DOA, DCA, DPA	0 1	1	×
0				
1				
P06.01	DPA	0 19	0	×
0				
1				
P06.01=1				
2				
3				
4				
5				
6				
7 9				
10				
11				
12				
13				
14				
15				
16				
6/16				
P10.00				
P10.01				
P10.00				
P10.01				
P06.02		2 300ms	10ms	×
DI DI P06.02				
P06.03	D11	0 30	7	×
P06.04	D12		8	×
P06.05	D13		11	×
P06.06	D14		12	×
P06.07	D15		13	×
P06.08	D16		14	×

Smile100

P06.09	D17		0	×
P06.10	D18		0	×
DI				
0				
1				
2				
3				
4				
5				
6				
7				
8				
9				
10				
11				
12				
13				
14				
15				
20				
21				
22				
21 22				
P06.11		0 4999ms	0	×
P06.11				
P00.02=1				
P00.06=0 P00.06=3				
P06.08 1000ms				
P05				
P06.12		0.1 99.9%	90.00%	○
P06.12 PA				
P06.01=0				
P06.13		0.1 2.0s	0.5s	○
P06.14		0 2	2	○
0				
1				
2				

P06.15	1	00000 11111	0	○
0 1 0 1 0 1 0 1 0 1 2s 1/3 0 1				
P06.16	2	00000 11111	1	○
0 1 0 1 0 1 Kp Kp 4 0 1 0 1 0 1 20 E0012 12 20				
P06.18		4 16kHz	8kHz	×
P06.19		2.50 15.00Hz	4.00Hz	○
P06.20		0 30s	0	○
≤ 2 2s				
P06.21		0 30%	10%	×

Smile100

P06.22		0.01 5.00Hz	1.00Hz	○
P06.23		0.01 5.00Hz	1.00Hz	○
P06.24		100 3999ms	2500ms	×
P06.25		0.10 15.00Hz	7.00Hz	○
P06.26		0 8%	0%	×

P06.21
P06.21 + P06.26

P06.27		10.00 50.00Hz	50.00Hz	×
P06.28	3	00000 11111	100	○

0

1

1

2.5s

CAN

0 CAN

1 CAN

0

1

0

1

0

1

10

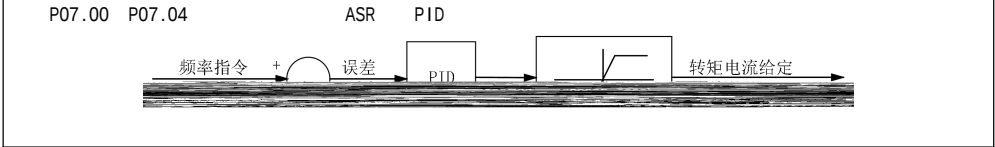
E10

E10

20

P07

P07.00	Kp	10 3000	200	○
P07.01	KI	0 1000	20	○
P07.02	Kp	10 3000	200	○
P07.03	KI	0 1000	20	○
P07.04		0.00 P00.04	8.00Hz	○



P07.00 P07.02 KP KP P07.01 P07.03 KI KI KI 0 KP KP KI KP KI				
P07.05	kp	10 9999	100	○
P07.06	KI	0 9999	100	○
P07.05 P07.06 PI KP KI KP KI KP KI KP KI PI				
P07.07		0.0 200.0%	120.00%	○
Smile100 P01.02				
P07.08		0 7	2	×
ASR P07.08=0				
P08				
P08.00		1.0s 999.9s	2.0s	○
P08.01		1.0s 999.9s	2.0s	○
P08.02		0 65535	0	○
P08.03		0 65535	0	○
P08.02 P08.02 1. “ RUN ” / / / / P08.00 P08.01 “ STOP ” P08.03 P08.02 P08.03				
P09				
P09.00	1	0 26	nan	*
P09.01	2	0 26	nan	*
P09.02	3	0 26	nan	*
P09.03	4	0 26	nan	*
P09.04	5	0 26	nan	*
0 1 E01 2 E02 3 E03 4 Z E04 5				

6	E06			
7	E07			
8		E08		
9	E09			
10	E10			
11	E11			
12	E12			
13				
14	EEPROM	E14		
15		E15		
16	E16			
17	E17			
18		E18		
19 21				
22	EEFOROM	E22		
23	E23			
24				
25				
26	E26			
100				
P09.05		0 999V	nanV	*
P09.06		0.00 99.99A	nanA	*
P09.07		0.00 99.99Hz	nanHz	*
P09.08		0.00 99.99Hz	nanHz	*
P09.09		0 65535	nan	*
P09.10	1	0 11111	nan	*
P09.11	2	0 111	nan	*
P09.12		0 111	nan	*
P09.13		0 9999	nan	*
P09.14		0 9999	nan	*
P09.15		0 23h	nanh	*
P09.16		0 9999	nan	*
P09.17		0.00 99.99	nan	*
P09.18		0.00 99.99	nan	*
P10				
P10.00		0 9999ms	0	×
P10.01		0 9999ms	0	×
P06.01 6 16	P10.00	P10.01	P10.00	

P10.01				
P10.02		0.1 5.0s	0.7s	○
P10.03		0.1 5.0s	0.7s	○
P10.04		0 9999	0	×
1	P02.05 2			
2	D	D01.00		
P10.05		0 1	0	×
0	P03.04/P04.04			
1				
P10.06		0 1	0	×
0				
1	P10.06 1	P10.02 P10.03		
P10.07		0 1	0	×
0				
1	1	1.1		
P10.08		0 1	0	×
0				
1	1	1.1		
P10.09		0 1	1	×
0				
1				
P10.10		0 2	0	×
0				
1	P10.11 P10.13			
2	P10.11 P10.13	P10.11 P10.13		
P10.10	2 1			
P10.11	U	1700 2200	1950	○
P10.12	V	1700 2200	1950	○
P10.13	W	1700 2200	1950	○
P10.14		0.01 0.50A	0.05A	×
P10.15		5 50%	20.00%	×
P10.16		0.0 2.0s	0.0s	×
P10.17		105 120%	110%	×
P10.18		0.0 2.0s	0.5s	×
P10.20	Z	0 1	0	×

Smile100

0 Z				
1 Z				
P10.21		0 1	0	×
0				
1				
P10.22	3	0 11111	0	○
0				
1				
1				
0				
1				
1				
200V				
0				
1				
0 M				
1 T				
P10.23	4	0 11110	0	○
UP DN				
0 UP DN 5S				
1 UP DN 5S				
0 0				
1 1				
2 2				
RT				
0				
1				
0				
1				
P10.24		30 150%	0%	*
P10.25		0 7	0	*
P10.26		0 65535	0	*
Bit0				
Bit1				
Bit2				

A

ISO9001 2008

18

24

- 1.
- 2.
- 3.
- 4.
- 5.

- 1.
- 2.
- 3.
- 4.
- 5.

SHENZHEN MEGMEET DRIVE TECHNOLOGY CO., LTD.

5

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